Location: ARC

Attendance: all

What has changed from last meeting:

* Quintin
  + Added functionality to change UI based on whether or not the tracked face is smiling
* Alex
  + Added functionality to stop listening when the app is minimized
  + Changed start listening command to “Okay Robocat”
  + Changed UI to show commands said, or if the command isn’t recognized
  + Fixed bug to ignore meow sound as a command
* Kurtis
  + Flipped emotion scaling to be more realistic

**Immediate goals:**

1. Group - Finish Sprint, sign up for student expo
2. Alex - Add privacy Policy to app description
3. Voice Recognition Team
   1. Alex - general active listening debugging, commands that move servos motors
   2. Kurtis - commands that move servos motors
4. Environmental Mapping
   1. Group - install arduino, test utrasonic beam signal
   2. zach.t013@gmail.com - add Battery stuff on master branch; add UI updates, battery level will change the “resting emotional level,” e.g. the base emotional level.
5. Facial Recognition/color Tracking
   1. Quintin - center on face with highest happiness rating, add in priority for highest happiness rating face, fix onPause() and onResume()
   2. Lukeshays@gmail.com - add color tracking to main app